

Multi-turn actuator			Motor									
Type	Output speed [rpm]	Max. torque [Nm]	Motor type	Nominal power ¹⁾ P _N [kW]	Speed [rpm]	Nominal current ²⁾ I _N [A]	Max. current ³⁾ I _{max} [A]	Starting current I _A [A]	cos φ	Overcurr. prot. device setting [A]	AUMA power class for switchgear	
											Contactors	Thyristor
SAEx 25.1	4.8	2,000	ADX0 90-8/130	1.1	840	7.0	9.0	17	0.48	7.0	A2	B2
	6.7					7.0	10	17	0.48	7.0	A2	B2
	9.6		ADX0 90-4/130	3.0	1,680	7.0	11	38	0.80	7.0	A2	B2
	13					7.0	12	38	0.80	7.0	A2	B2
	19		ADX0 90-2/130	4.0	3,360	10	16	58	0.78	10	A2	B3
	26					10	20	58	0.78	10	A2	B3
	38		ADX0 132-4/140	7.5	1,680	22	40	120	0.65	22	A3	–
	54					22	48	120	0.65	22	A3	–
75	ADX0 132-2/180	15	3,360	30	60	190	0.90	30	A3	–		
108				30	70	190	0.90	30	A3	–		
SAEx 30.1	4.8	4,000	ADX0 112-8/140	2.2	840	11	15	36	0.58	11	A2	B3
	6.7					11	16	36	0.58	11	A2	B3
	9.6		ADX0 112-4/110	5.5	1,680	13	20	60	0.77	13	A2	B3
	13					13	23	60	0.77	13	A2	B3
	19		ADX0 112-2/140	7.5	3,360	18	28	120	0.78	18	A2	–
	26					18	30	120	0.78	18	A2	–
	38		ADX0 160-4/160	15	1,680	44	58	200	0.63	44	A4	–
	54					44	67	200	0.63	44	A4	–
75	ADX0 160-2/215	30	3,360	65	130	370	0.88	65	A4	–		
108				65	150	370	0.88	65	A4	–		
SAEx 35.1	4.8	8,000	ADX0 132-8/150	4.0	840	20	30	70	0.44	20	A2	–
	6.7					20	35	70	0.44	20	A2	–
	9.6		ADX0 132-4/140	7.5	1,680	22	48	120	0.65	22	A3	–
	13					22	55	120	0.65	22	A3	–
	19		ADX0 132-2/180	15	3,360	30	60	190	0.90	30	A3	–
	26					30	70	190	0.90	30	A3	–
38	ADX0 160-2/214	20	3,360	40	80	260	0.90	40	A4	–		
54				40	95	260	0.90	40	A4	–		
SAEx 40.1	4.8	16,000	ADX0 160-8/165	7.5	840	30	55	93	0.50	30	A3	–
	6.7					30	58	93	0.50	30	A3	–
	9.6		ADX0 160-4/160	15	1,680	44	70	200	0.63	44	A4	–
	13					44	87	200	0.63	44	A4	–
	19		ADX0 160-2/215	30	3,360	65	150	370	0.88	65	A4	–
	26					65	170	370	0.88	65	A4	–
38	ADX0 160-2/215	30	3,360	65	200	370	0.88	65	A4	–		

Notes on table

1) Nominal power P _N	Mechanical power output at motor shaft at running torque of multi-turn actuator (corresponds to approx. 50 % of maximum torque). The consumed electrical power can be calculated using the following formula: $P = U \times I \times \cos \varphi \times \sqrt{3}$
2) Nominal current I _N	Current at running torque
3) Max. current I _{max}	Current at maximum torque

Notes on installation and sizing

Motor data	Motor data is approximate. Due to usual manufacturing tolerances, there may be deviations from the values given.
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Thermoswitches/PTC thermistors	<p>To protect against overheating, thermoswitches or PTC thermistors are embedded in the motor windings.</p> <p>Actuators without integral controls (AUMA NORM): Thermoswitches or PTC thermistors have to be considered within the external controls (refer to terminal plan).</p> <p>Note: Failure to connect thermoswitches or PTC thermistors shall void the warranty for the motor. According to EN 60079-14, a thermal overcurrent protection device (e.g. motor protection switch) must be installed for explosion-proof actuators in addition to the thermoswitches. PTC thermistors additionally require a suitable tripping device in the controls.</p> <p>Rating of the thermoswitches</p> <table border="1" data-bbox="454 472 1182 584"> <thead> <tr> <th colspan="2">AC current</th> <th colspan="2">DC current</th> </tr> </thead> <tbody> <tr> <td colspan="2">250 V, 50 – 60 Hz</td> <td>60 V</td> <td>1.0 A</td> </tr> <tr> <td>cos φ = 1</td> <td>2.5 A</td> <td>42 V</td> <td>1.2 A</td> </tr> <tr> <td>cos φ = 0.6</td> <td>1.6 A</td> <td>24 V</td> <td>1.5 A</td> </tr> </tbody> </table> <p>Actuators with AMExC or ACExC integral controls: Thermal motor protection is already integrated.</p>	AC current		DC current		250 V, 50 – 60 Hz		60 V	1.0 A	cos φ = 1	2.5 A	42 V	1.2 A	cos φ = 0.6	1.6 A	24 V	1.5 A																											
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Mains voltage, mains frequency	<p>Permissible variation of mains voltage: $\pm 10\%$ Permissible variation of mains frequency: $\pm 5\%$</p>																																											
Switchgear sizing	<p>For motor operation, reversing contactors (mechanically, electrically and electronically locked) or thyristors (electronically locked) can be used.</p> <p>Actuators without integral controls (AUMA NORM): Switchgear are supplied by the customer. We recommend specification of switchgear suitable for their rated operating power/motor power in compliance with the assigned AUMA power class. Switchgear assignment to AUMA power classes:</p> <table border="1" data-bbox="454 952 1418 1451"> <thead> <tr> <th rowspan="2">AUMA power class</th> <th rowspan="2">Reversing contactor Rated operating power acc. to EN 60947-4-1 Utilization category AC-3</th> <th colspan="2">Reversing contactor Motor power according to UL/CSA at</th> </tr> <tr> <th>480 V AC</th> <th>600 V AC</th> </tr> </thead> <tbody> <tr> <td></td> <td>400 V AC</td> <td></td> <td></td> </tr> <tr> <td>A1</td> <td>4.0 kW</td> <td>5.0 hp</td> <td>5.0 hp</td> </tr> <tr> <td>A2</td> <td>7.5 kW</td> <td>10 hp</td> <td>10 hp</td> </tr> <tr> <td>A3</td> <td>15 kW</td> <td>20 hp</td> <td>25 hp</td> </tr> <tr> <td>A4</td> <td>30 kW</td> <td>60 hp</td> <td>60 hp</td> </tr> <tr> <td>A5</td> <td>55 kW</td> <td>75 hp</td> <td>100 hp</td> </tr> <tr> <td>A6</td> <td>75 kW</td> <td>100 hp</td> <td>125 hp</td> </tr> </tbody> </table> <table border="1" data-bbox="454 1243 959 1451"> <thead> <tr> <th rowspan="2">AUMA power class</th> <th rowspan="2">Thyristor Rated operating current acc. to EN 60947-4-2 Utilization category AC-53a</th> </tr> <tr> <th>400 V AC</th> </tr> </thead> <tbody> <tr> <td>B1</td> <td>6 A</td> </tr> <tr> <td>B2</td> <td>8.5 A</td> </tr> <tr> <td>B3</td> <td>16 A</td> </tr> </tbody> </table> <p>Actuators with AMExC or ACExC integral controls: Required switchgear in power classes A1 – A3 or B1 – B3 are already integrated in AMExC or ACExC controls. For switchgear of power classes A4 – A6, a control box is additionally required. For actuators with AMExC integral actuator controls and installed switchgear in AUMA power class A3, an optional thermal overcurrent protection device cannot be directly integrated within the AMExC. An additional control box is required. However, ACExC actuator controls can be used instead of AMExC controls. When opting for ACExC controls, the additional control box can be omitted.</p>	AUMA power class	Reversing contactor Rated operating power acc. to EN 60947-4-1 Utilization category AC-3	Reversing contactor Motor power according to UL/CSA at		480 V AC	600 V AC		400 V AC			A1	4.0 kW	5.0 hp	5.0 hp	A2	7.5 kW	10 hp	10 hp	A3	15 kW	20 hp	25 hp	A4	30 kW	60 hp	60 hp	A5	55 kW	75 hp	100 hp	A6	75 kW	100 hp	125 hp	AUMA power class	Thyristor Rated operating current acc. to EN 60947-4-2 Utilization category AC-53a	400 V AC	B1	6 A	B2	8.5 A	B3	16 A
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